

EE 230

Lecture 35

Small Signal Models
Small Signal Analysis

Small-signal Operation of Nonlinear Circuits

- Small-signal principles
- Example Circuit
- Small-Signal Models
- Small-Signal Analysis of Nonlinear Circuits

Review from Last Time:

Solution for the example was based upon solving the nonlinear circuit for V_{OUT} and then linearizing the solution by doing a Taylor's series expansion

- Solution of nonlinear equations very involved with two or more nonlinear devices*
- Taylor's series linearization can get very tedious if multiple nonlinear devices are present*

Standard Approach to small-signal analysis of nonlinear networks

- 1. Solve nonlinear network*
- 2. Linearize solution*

Alternative Approach to small-signal analysis of nonlinear networks

- 1. Linearize nonlinear devices*
- 2. Replace all devices with small-signal equivalent*
- 3. Solve linear small-signal network*

Review from Last Time:

Alternative Approach to small-signal analysis of nonlinear networks

1. *Linearize nonlinear devices*
2. *Replace all devices with small-signal equivalent*
3. *Solve linear small-signal network*

- **Must only develop linearized model once for any nonlinear device**

e.g. once for a MOSFET, once for a JFET, and once for a BJT

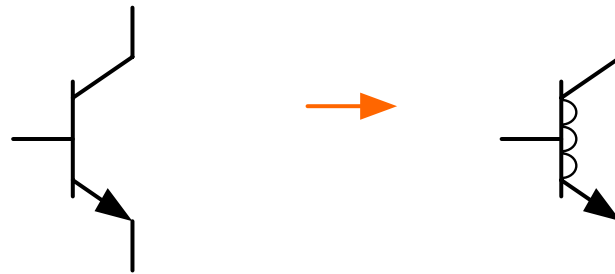
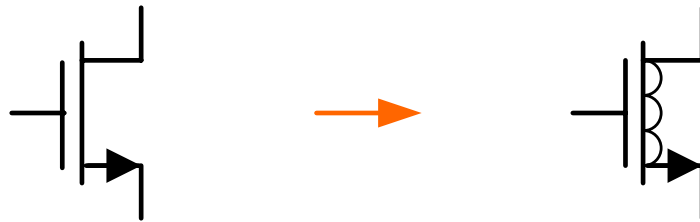
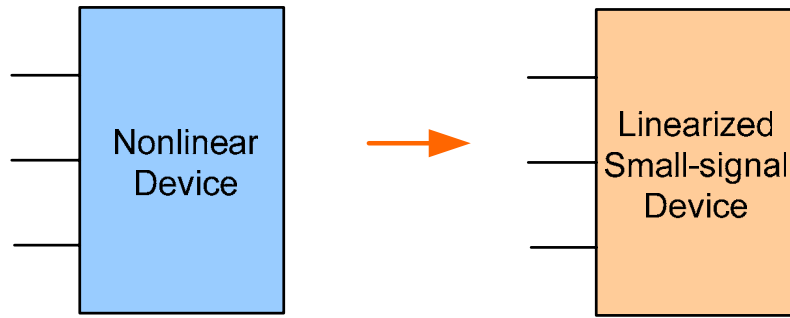
Linearized model for nonlinear device termed “small-signal model”

derivation of small-signal model for most nonlinear devices is less complicated than solving even one simple nonlinear circuit

- **Solution of linear network much easier than solution of nonlinear network**
















Review from Last Time:

Linearized nonlinear devices



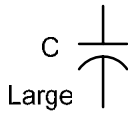


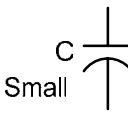
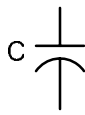

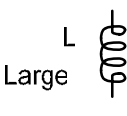


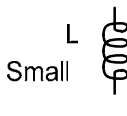
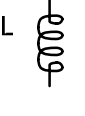


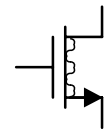
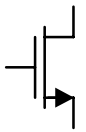
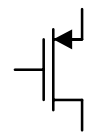
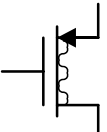
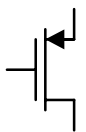
Review from Last Time:

Dc and small-signal equivalent elements

	Element	ss equivalent	dc equivalent
dc Voltage Source	V_{DC} 		V_{DC} 
ac Voltage Source	V_{AC} 	V_{AC} 	
dc Current Source	I_{DC} 		I_{DC} 
ac Current Source	I_{AC} 	I_{AC} 	
Resistor	R 	R 	R 

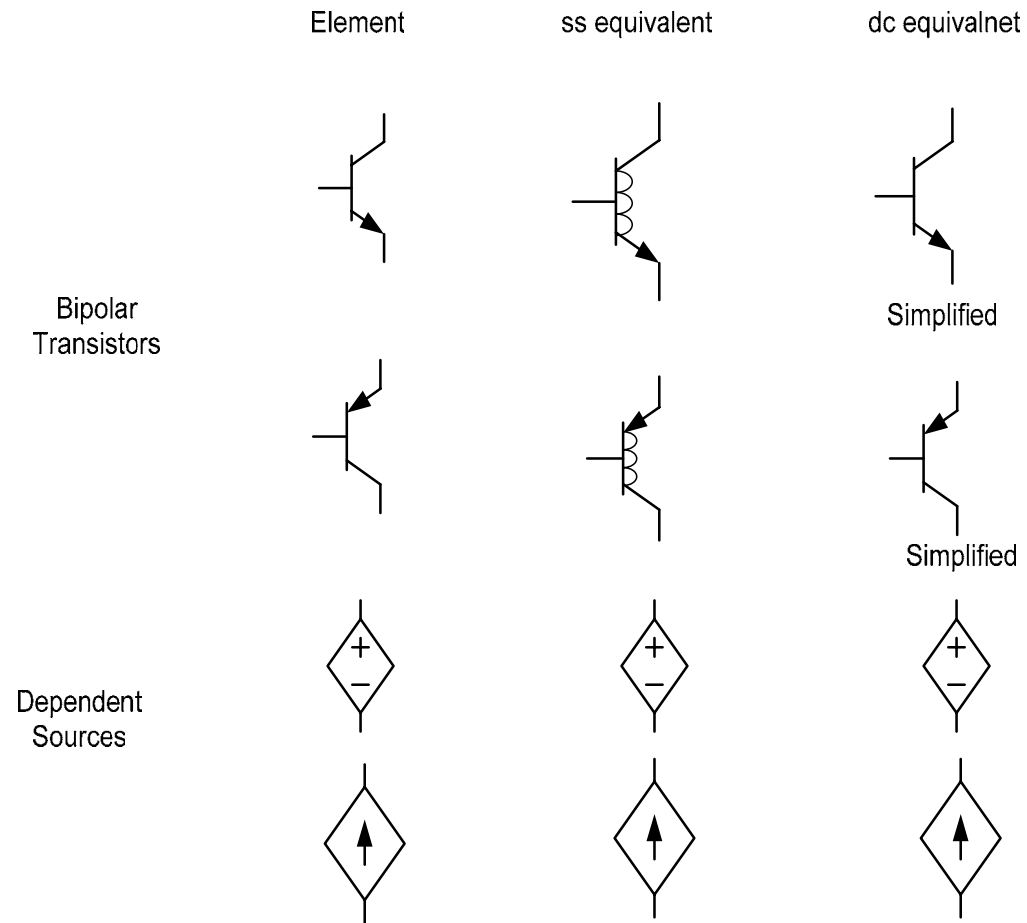
Review from Last Time:

Dc and small-signal equivalent elements

	Element	ss equivalent	dc equivalent
Capacitors	<p>C</p> <p>Large</p> 		
	<p>C</p> <p>Small</p> 	<p>C</p> 	
Inductors	<p>L</p> <p>Large</p> 		
	<p>L</p> <p>Small</p> 	<p>L</p> 	
MOS Transistors			 <p>Simplified</p>
			 <p>Simplified</p>

Review from Last Time:

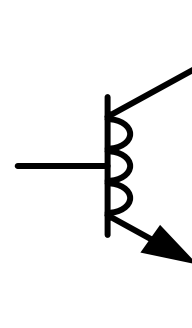
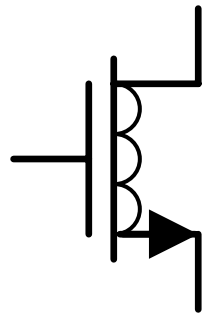
Dc and small-signal equivalent elements



Review from Last Time:

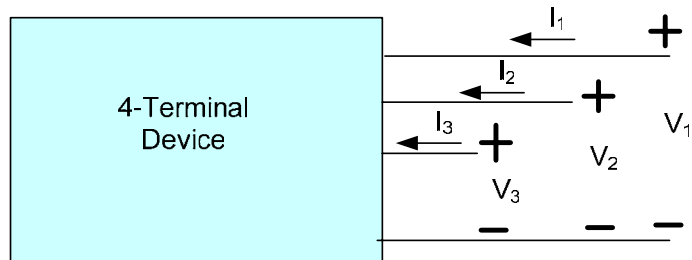
How is the small-signal equivalent circuit obtained from the nonlinear circuit?

What is the small-signal equivalent of the MOSFET and BJT ?



Review from Last Time:

4-terminal small-signal network summary



$$\left. \begin{aligned} \mathbf{I}_1 &= \mathbf{f}_1(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) \\ \mathbf{I}_2 &= \mathbf{f}_2(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) \\ \mathbf{I}_3 &= \mathbf{f}_3(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) \end{aligned} \right\}$$

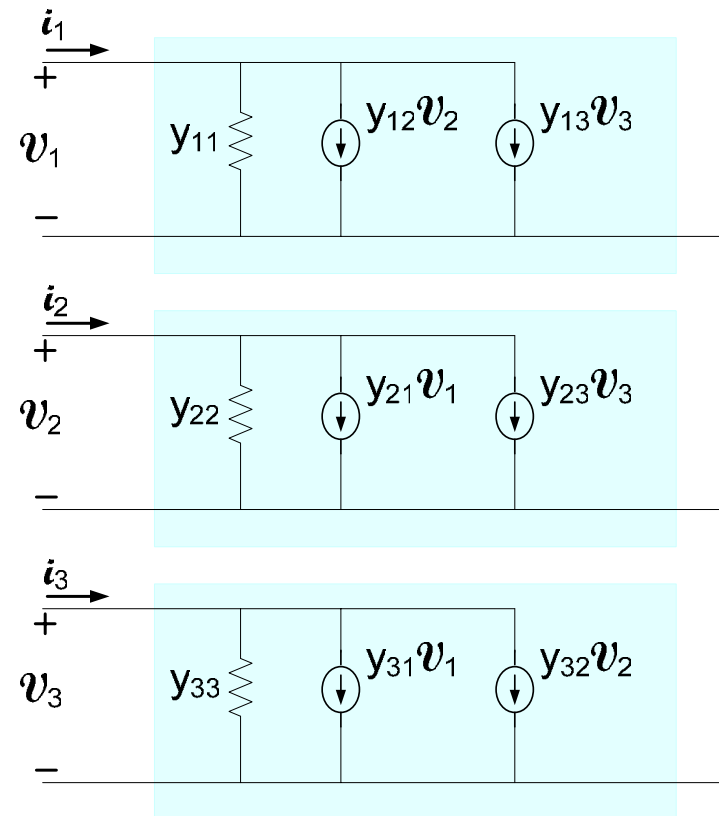
Small signal model:

$$\mathbf{i}_1 = y_{11} \mathbf{u}_1 + y_{12} \mathbf{u}_2 + y_{13} \mathbf{u}_3$$

$$\mathbf{i}_2 = y_{21} \mathbf{u}_1 + y_{22} \mathbf{u}_2 + y_{23} \mathbf{u}_3$$

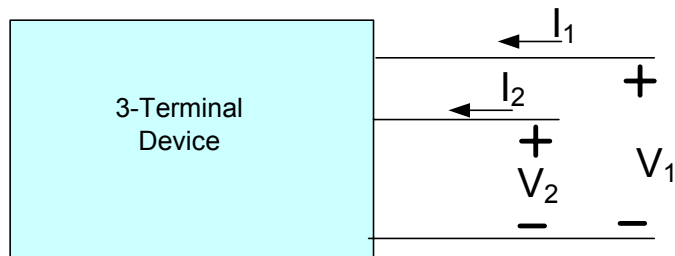
$$\mathbf{i}_3 = y_{31} \mathbf{u}_1 + y_{32} \mathbf{u}_2 + y_{33} \mathbf{u}_3$$

$$\mathbf{y}_{ij} = \left. \frac{\partial \mathbf{f}_i(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3)}{\partial \mathbf{V}_j} \right|_{\bar{\mathbf{V}} = \bar{\mathbf{V}}_Q}$$



Review from Last Time:

3-terminal small-signal network summary

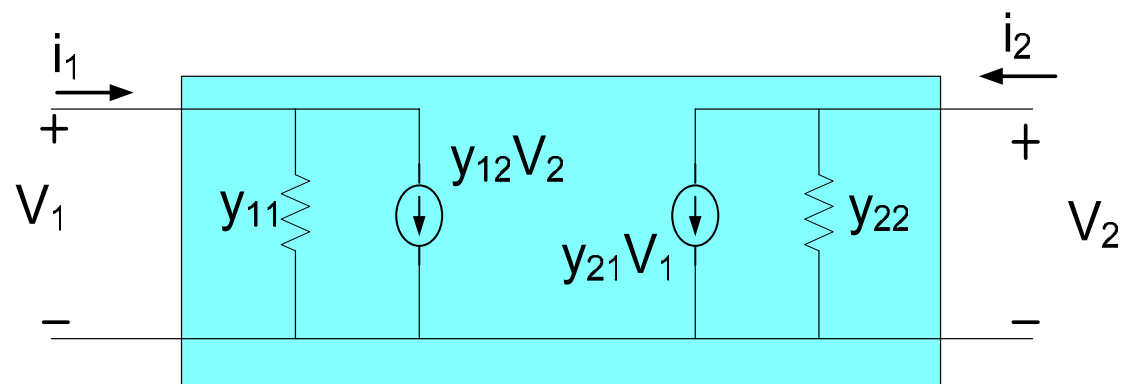


$$\left. \begin{aligned} \mathbf{I}_1 &= \mathbf{f}_1(\mathbf{V}_1, \mathbf{V}_2) \\ \mathbf{I}_2 &= \mathbf{f}_2(\mathbf{V}_1, \mathbf{V}_2) \end{aligned} \right\}$$

Small signal model:

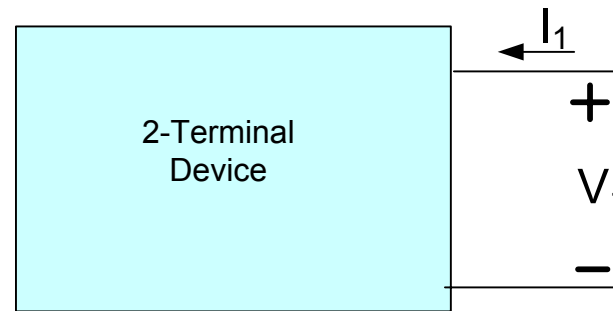
$$\begin{aligned} \mathbf{i}_1 &= y_{11} \mathbf{v}_1 + y_{12} \mathbf{v}_2 \\ \mathbf{i}_2 &= y_{21} \mathbf{v}_1 + y_{22} \mathbf{v}_2 \end{aligned}$$

$$\mathbf{y}_{ij} = \left. \frac{\partial \mathbf{f}_i(\mathbf{V}_1, \mathbf{V}_2)}{\partial \mathbf{V}_j} \right|_{\bar{\mathbf{v}} = \bar{\mathbf{v}}_q}$$



Review from Last Time:
2-terminal network summary

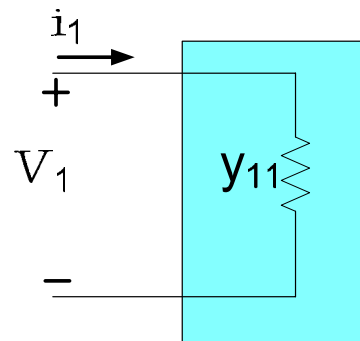
Small-Signal Model



$$\mathbf{i}_1 = \mathbf{y}_{11} \mathbf{v}_1$$

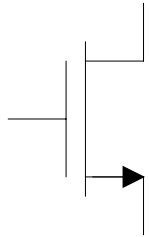
$$\mathbf{y}_{11} = \left. \frac{\partial \mathbf{f}_1(V_1)}{\partial V_1} \right|_{\bar{V} = \bar{V}_Q} \quad \bar{V} = V_{1Q}$$

A Small Signal Equivalent Circuit



Review from Last Time:

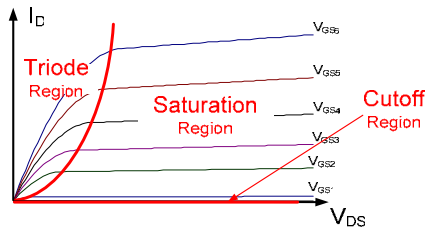
Small Signal Model of MOSFET



Large Signal Model

$$I_G = 0$$

3-terminal device

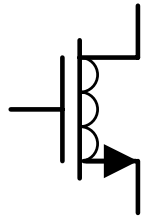


$$I_D = \begin{cases} 0 & V_{GS} \leq V_T \\ \mu C_{OX} \frac{W}{L} \left(V_{GS} - V_T - \frac{V_{DS}}{2} \right) V_{DS} & V_{GS} \geq V_T, V_{DS} < V_{GS} - V_T \\ \mu C_{OX} \frac{W}{2L} (V_{GS} - V_T)^2 (1 + \lambda V_{DS}) & V_{GS} \geq V_T, V_{DS} \geq V_{GS} - V_T \end{cases}$$

MOSFET is usually operated in saturation region in linear applications where a small-signal model is needed so will develop the small-signal model in the saturation region

Review from Last Time:

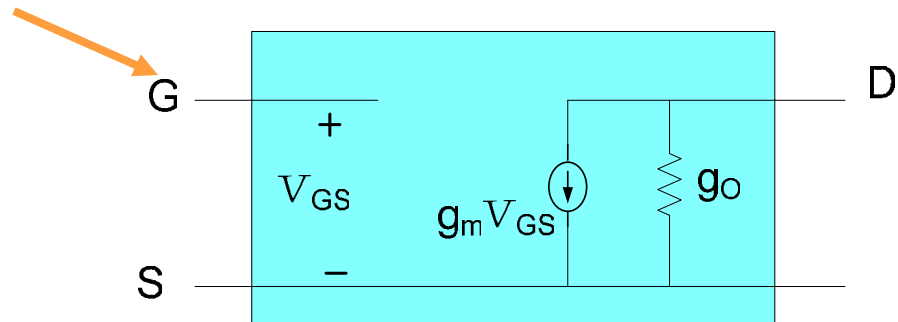
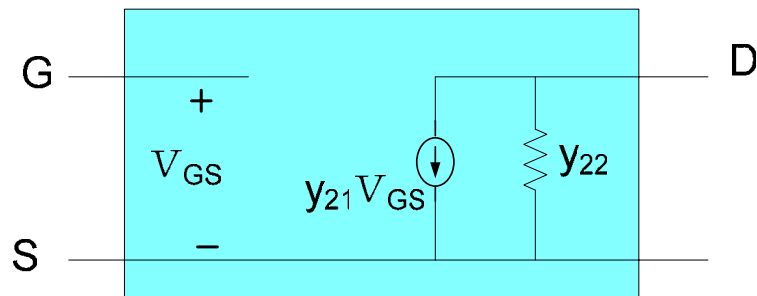
Small Signal Model of MOSFET



by convention, $y_{21} = g_m$, $y_{22} = g_o$

$$y_{21} \cong g_m = \mu C_{ox} \frac{W}{L} (V_{GSQ} - V_T)$$

$$y_{22} = g_o \cong \lambda I_{DQ}$$

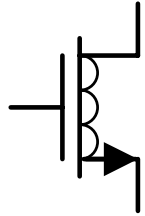


$$i_G = 0$$

$$i_D = g_m v_{GS} + g_o v_{DS}$$

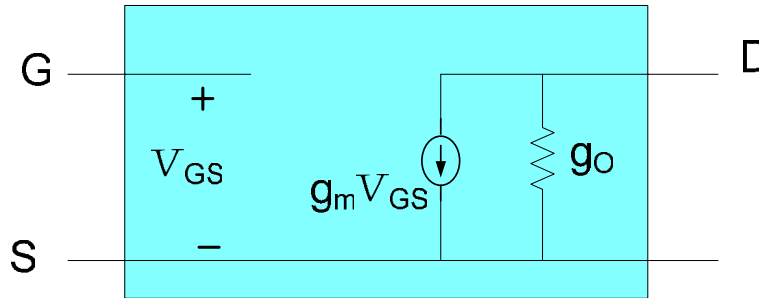
Review from Last Time:

Small Signal Model of MOSFET



$$g_m = \mu C_{\text{ox}} \frac{W}{L} (V_{\text{GSQ}} - V_T)$$

$$g_o \cong \lambda I_{\text{DQ}}$$



Alternate equivalent expressions:

$$I_{\text{DQ}} = \mu C_{\text{ox}} \frac{W}{2L} (V_{\text{GSQ}} - V_T)^2 (1 + \lambda V_{\text{DSQ}}) \cong \mu C_{\text{ox}} \frac{W}{2L} (V_{\text{GSQ}} - V_T)^2$$

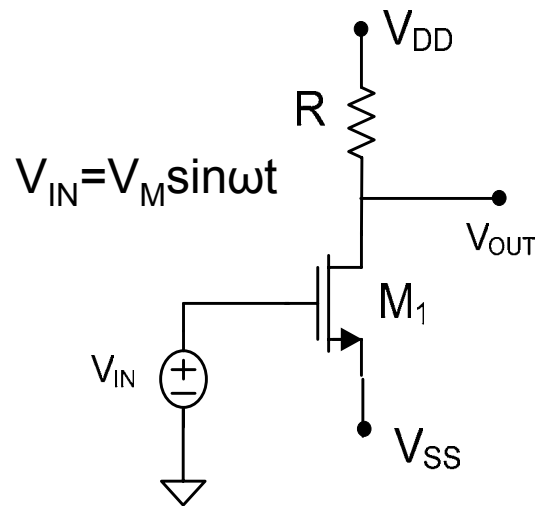
$$g_m = \mu C_{\text{ox}} \frac{W}{L} (V_{\text{GSQ}} - V_T)$$

$$g_m = \sqrt{2\mu C_{\text{ox}} \frac{W}{L}} \cdot \sqrt{I_{\text{DQ}}}$$

$$g_m = \frac{2I_{\text{DQ}}}{V_{\text{GSQ}} - V_T}$$

Review from Last Time:

Small signal analysis example



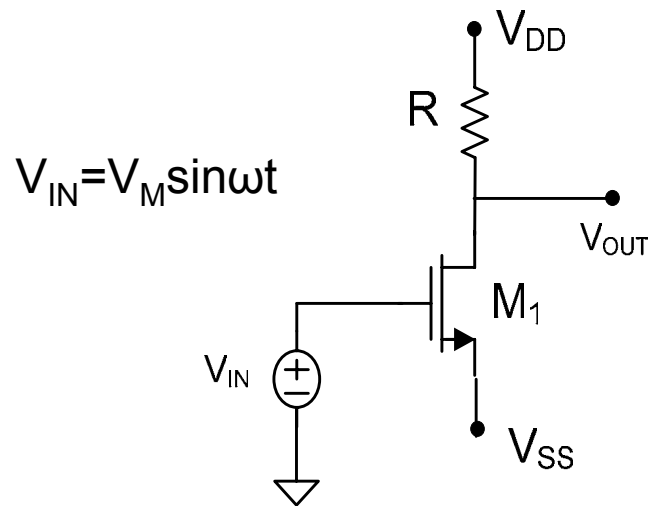
$$A_v = \frac{2I_{DQ} R}{[V_{SS} + V_T]}$$

Observe the small signal voltage gain is twice the Quiescent voltage across R divided by $V_{SS} + V_T$

- This analysis which required linearization of a nonlinear output voltage is quite tedious.
- This approach becomes unwieldy for even slightly more complicated circuits
- A much easier approach based upon the development of small signal models will provide the same results, provide more insight into both analysis and design, and result in a dramatic reduction in computational requirements

Consider again:

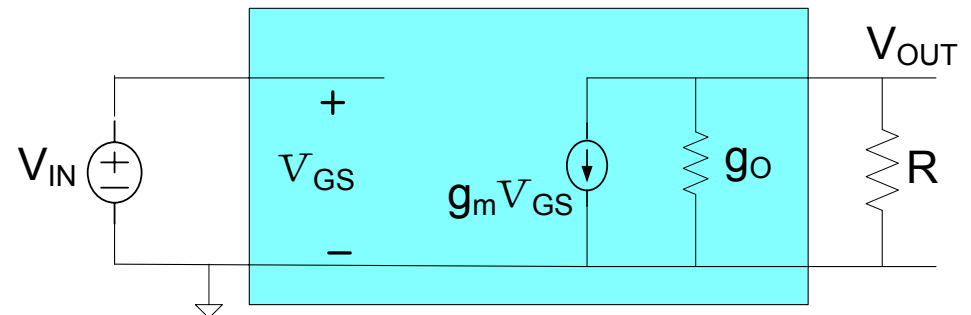
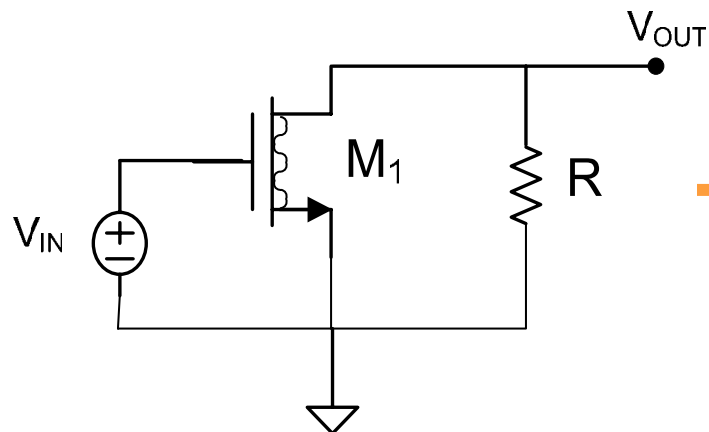
Small signal analysis example



$$A_v = \frac{2I_{DQ} R}{[V_{SS} + V_T]}$$

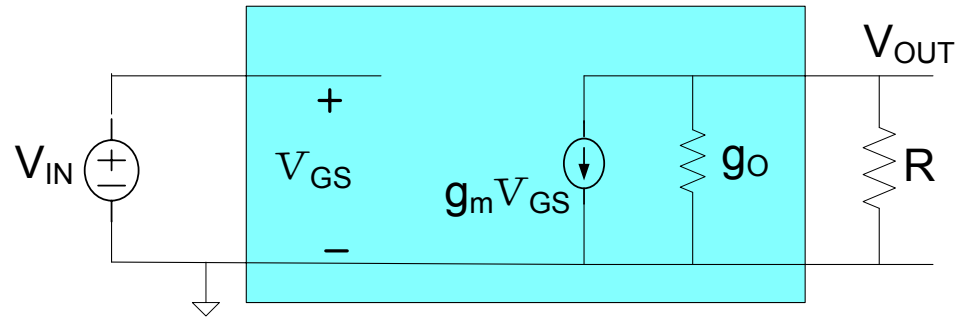
Derived for $\lambda=0$

$$I_{DQ} = \mu C_{ox} \frac{W}{2L} (V_{GSQ} - V_T)^2$$



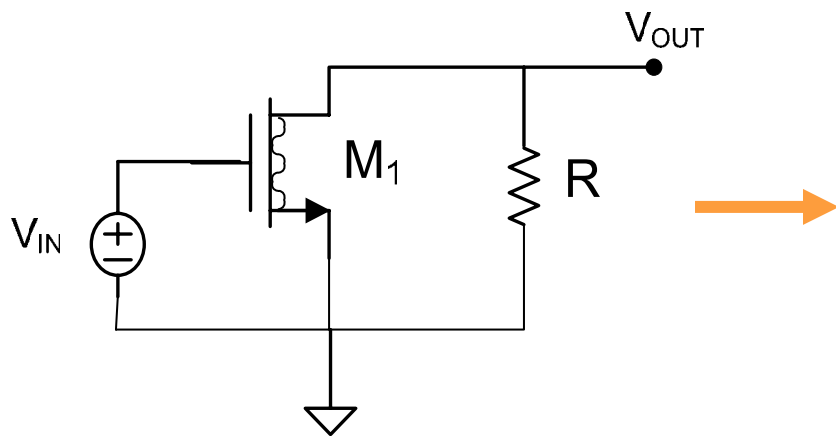
Consider again:

Small signal analysis example



$$A_v = \frac{V_{OUT}}{V_{IN}} = -\frac{g_m}{g_o + 1/R}$$

For $\lambda=0$, $g_o = \lambda I_{DQ} = 0$



$$A_v = \frac{V_{OUT}}{V_{IN}} = -g_m R$$

but

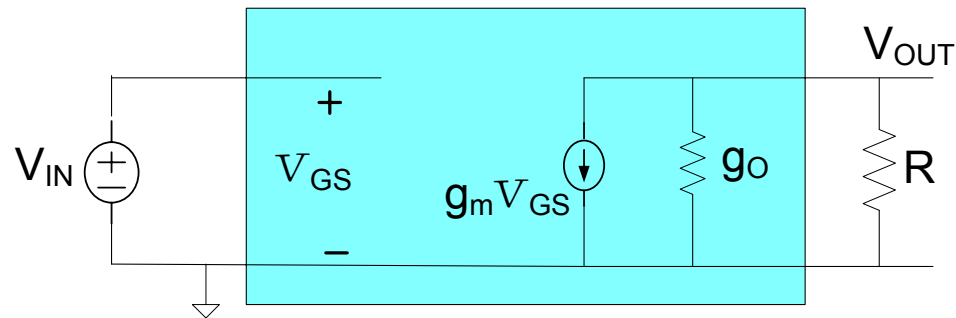
$$g_m = \frac{2I_{DQ}}{V_{GSQ} - V_T} \quad V_{GSQ} = -V_{SS}$$

thus

$$A_v = \frac{2I_{DQ} R}{[V_{SS} + V_T]}$$

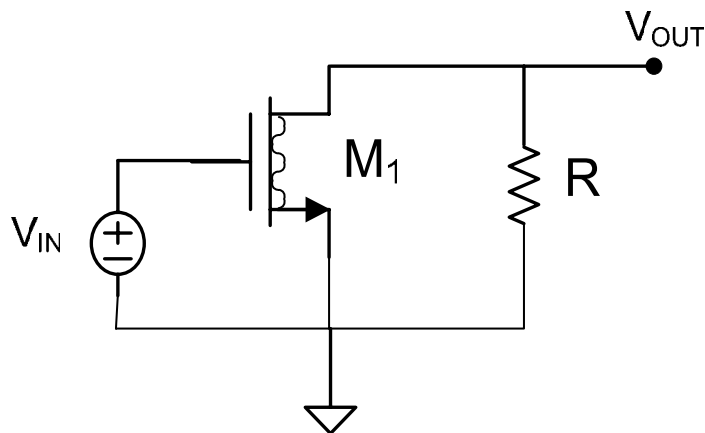
Consider again:

Small signal analysis example



$$A_v = \frac{V_{OUT}}{V_{IN}} = -\frac{g_m}{g_o + 1/R}$$

For $\lambda=0$, $g_o = \lambda I_{DQ} = 0$



$$A_v = \frac{2I_{DQ} R}{[V_{SS} + V_T]}$$

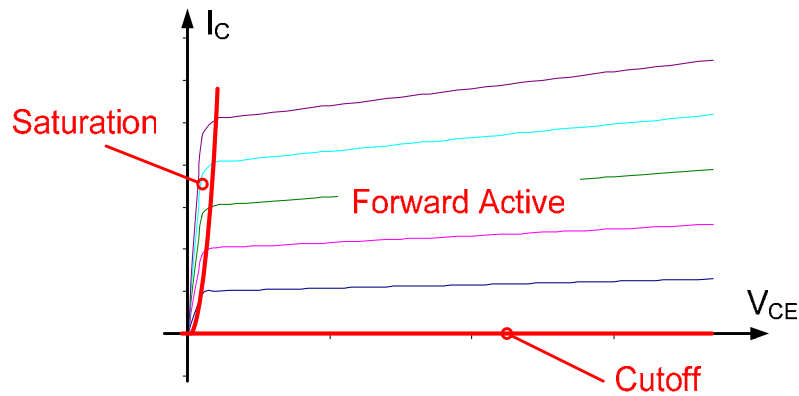
Same expression as derived before

More accurate gain can be obtained if λ effects are included and does not significantly increase complexity of small signal analysis

Small Signal Model of BJT



3-terminal device



Forward Active Model:

$$I_C = J_S A_E e^{\frac{V_{BE}}{V_t}} \left(1 + \frac{V_{CE}}{V_{AF}} \right)$$
$$I_B = \frac{J_S A_E}{\beta} e^{\frac{V_{BE}}{V_t}}$$

*Usually operated in Forward Active Region
when small-signal model is needed*

Small Signal Model of BJT

$$I_1 = f_1(V_1, V_2) \quad \longleftrightarrow \quad I_B = \frac{J_S A_E}{\beta} e^{\frac{V_{BE}}{V_t}}$$

$$I_2 = f_2(V_1, V_2) \quad \longleftrightarrow \quad I_C = J_S A_E e^{\frac{V_{BE}}{V_t}} \left(1 + \frac{V_{CE}}{V_{AF}} \right)$$

Small-signal model:

$$y_{ij} = \left. \frac{\partial f_i(V_1, V_2)}{\partial V_j} \right|_{\bar{V}=\bar{V}_Q}$$

$$y_{11} = g_\pi = \left. \frac{\partial I_B}{\partial V_{BE}} \right|_{\bar{V}=\bar{V}_Q}$$

$$y_{12} = \left. \frac{\partial I_B}{\partial V_{CE}} \right|_{\bar{V}=\bar{V}_Q}$$

$$y_{21} = g_m = \left. \frac{\partial I_C}{\partial V_{BE}} \right|_{\bar{V}=\bar{V}_Q}$$

$$y_{22} = g_o = \left. \frac{\partial I_C}{\partial V_{CE}} \right|_{\bar{V}=\bar{V}_Q}$$

Small Signal Model of BJT

$$I_B = \frac{J_S A_E}{\beta} e^{\frac{V_{BE}}{V_t}}$$

$$I_C = J_S A_E e^{\frac{V_{BE}}{V_t}} \left(1 + \frac{V_{CE}}{V_{AF}} \right)$$

Small-signal model:

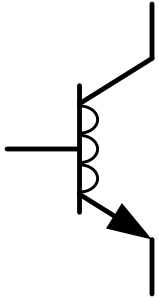
$$g_\pi = \left. \frac{\partial I_B}{\partial V_{BE}} \right|_{\bar{V}=\bar{V}_Q} = \frac{1}{V_t} \frac{J_S A_E}{\beta} e^{\frac{V_{BE}}{V_t}} \bigg|_{\bar{V}=\bar{V}_Q} = \frac{I_{BQ}}{V_t} \cong \frac{I_{CQ}}{\beta V_t}$$

$$y_{12} = \left. \frac{\partial I_B}{\partial V_{CE}} \right|_{\bar{V}=\bar{V}_Q} = 0$$

$$y_{21} = g_m = \left. \frac{\partial I_C}{\partial V_{BE}} \right|_{\bar{V}=\bar{V}_Q} = \frac{1}{V_t} J_S A_E e^{\frac{V_{BE}}{V_t}} \left(1 + \frac{V_{CE}}{V_{AF}} \right) \bigg|_{\bar{V}=\bar{V}_Q} = \frac{I_{CQ}}{V_t}$$

$$y_{22} = g_o = \left. \frac{\partial I_C}{\partial V_{CE}} \right|_{\bar{V}=\bar{V}_Q} = \frac{J_S A_E e^{\frac{V_{BE}}{V_t}}}{V_{AF}} \bigg|_{\bar{V}=\bar{V}_Q} \cong \frac{I_{CQ}}{V_{AF}}$$

Small Signal Model of BJT



$$\begin{aligned} i_B &= y_{11} v_{BE} + y_{12} v_{CE} \\ i_C &= y_{21} v_{BE} + y_{22} v_{CE} \end{aligned}$$

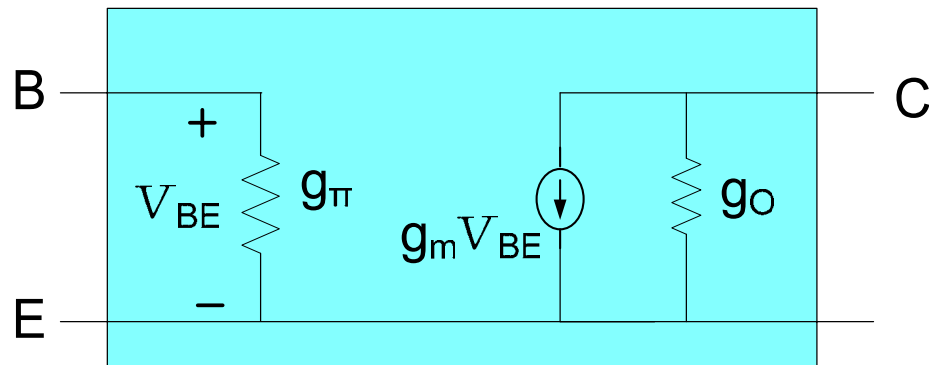


$$\begin{aligned} i_B &= g_\pi v_{BE} \\ i_C &= g_m v_{BE} + g_o v_{CE} \end{aligned}$$

$$g_\pi = \frac{I_{CQ}}{\beta V_t}$$

$$g_m = \frac{I_{CQ}}{V_t}$$

$$g_o = \frac{I_{CQ}}{V_{AF}}$$



Small-signal Operation of Nonlinear Circuits

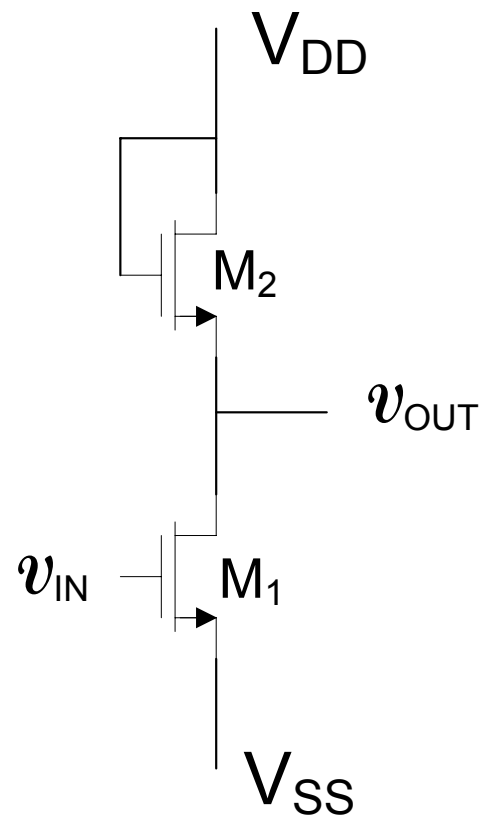
- Small-signal principles
 - Example Circuit
 - Small-Signal Models
- Small-Signal Analysis of Nonlinear Circuits

Recall:

Alternative Approach to small-signal analysis of nonlinear networks

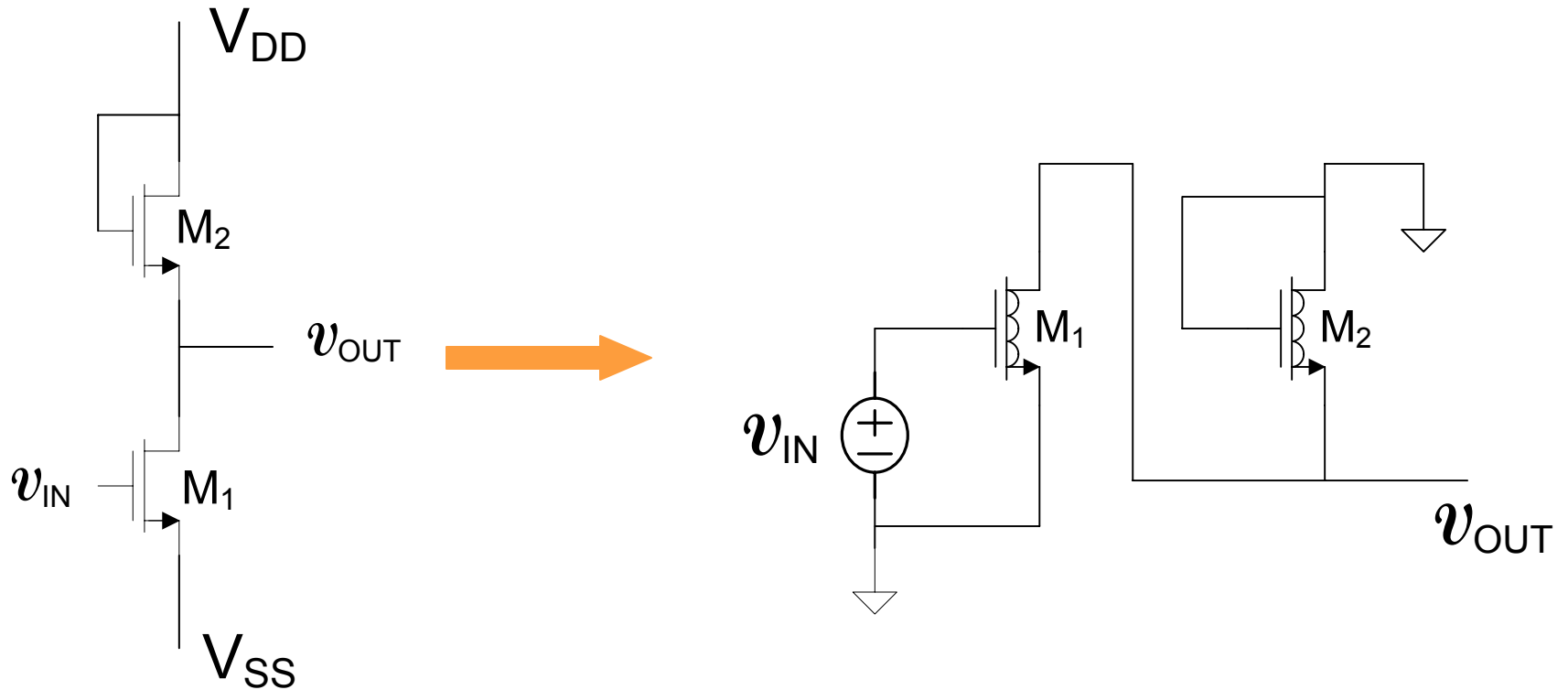
- 1. Linearize nonlinear devices**
(have small-signal model for key devices!)
- 2. Replace all devices with small-signal equivalent**
- 3. Solve linear small-signal network**

Example:



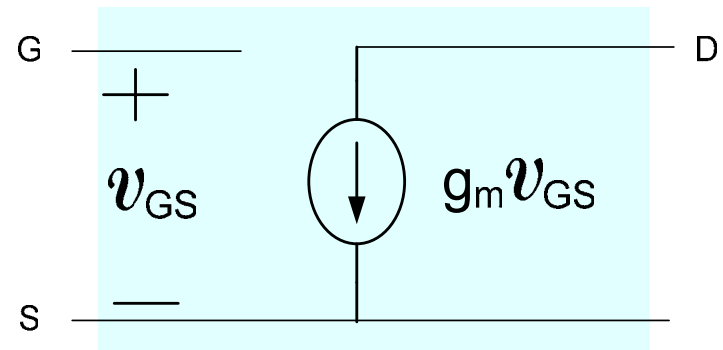
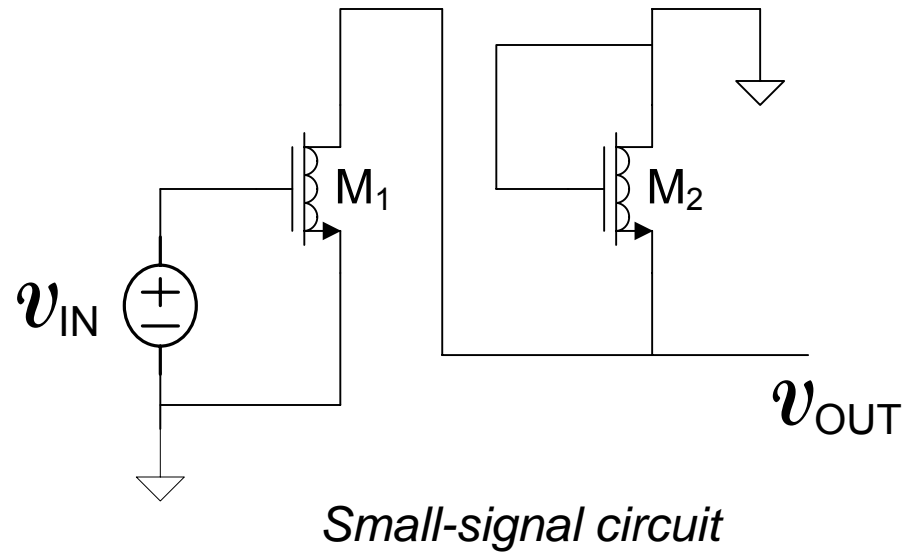
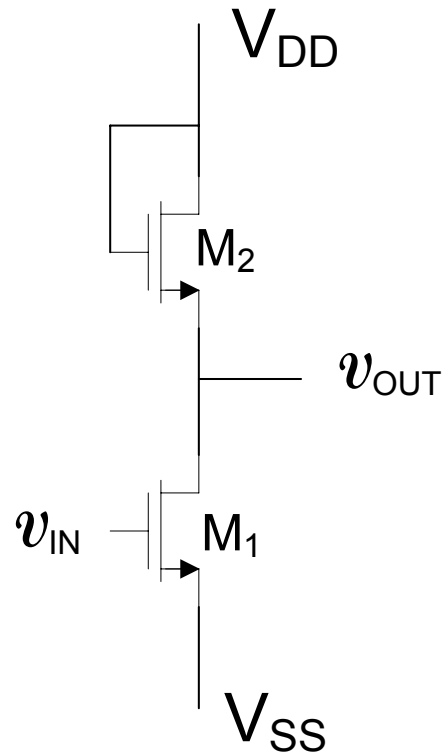
Determine the small signal voltage gain $A_V = v_{OUT}/v_{IN}$. Assume M_1 and M_2 are operating in the saturation region and that $\lambda=0$

Example: Determine the small signal voltage gain $A_V = v_{OUT}/v_{IN}$. Assume M_1 and M_2 are operating in the saturation region and that $\lambda=0$



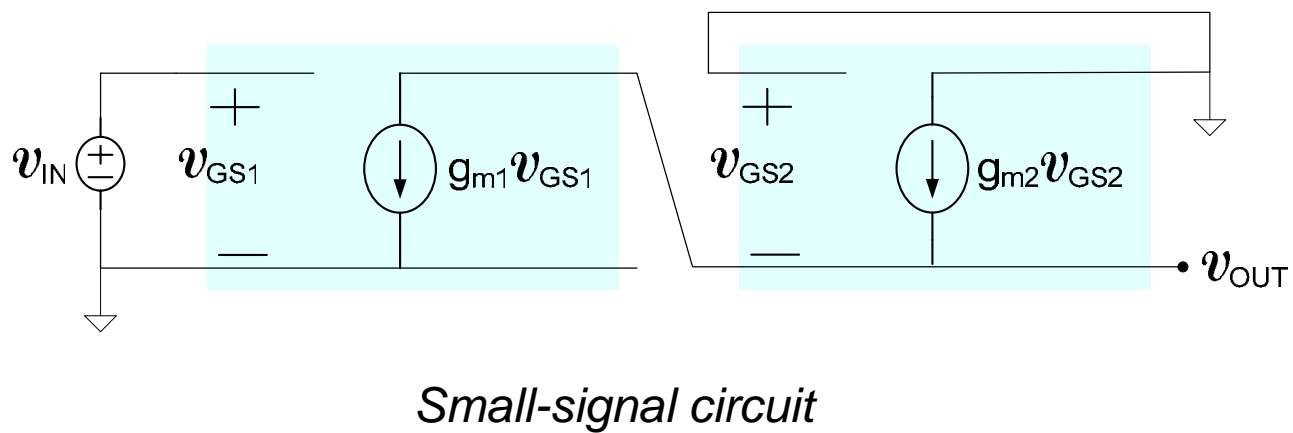
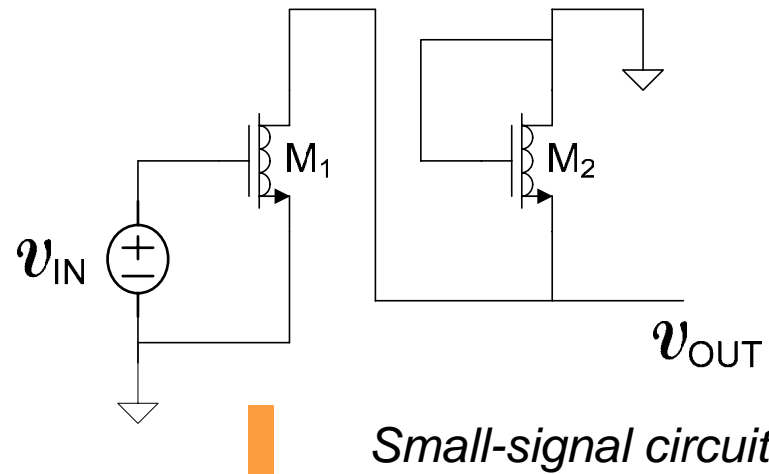
Small-signal circuit

Example: Determine the small signal voltage gain $A_V = v_{OUT}/v_{IN}$. Assume M_1 and M_2 are operating in the saturation region and that $\lambda=0$

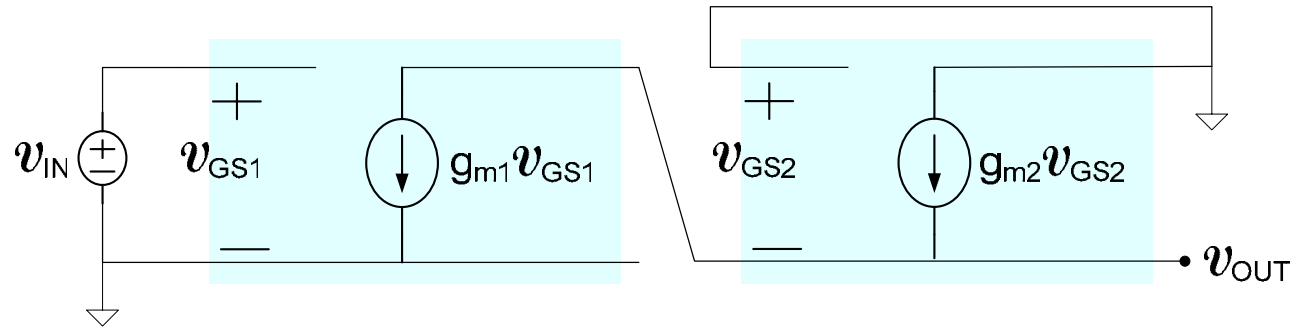


Small-signal MOSFET model for $\lambda=0$

Example: Determine the small signal voltage gain $A_V = v_{OUT}/v_{IN}$. Assume M_1 and M_2 are operating in the saturation region and that $\lambda=0$



Example:



Small-signal circuit

Analysis:

By KCL

$$g_{m1} v_{GS1} = g_{m2} v_{GS2}$$

but

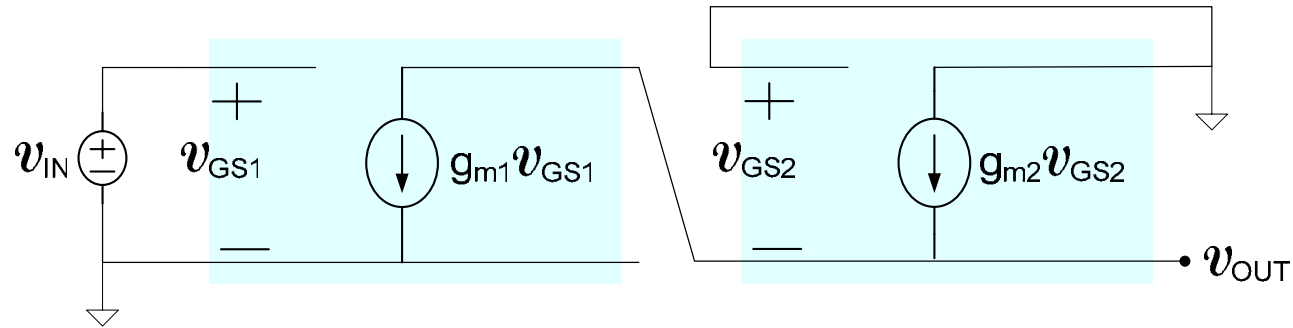
$$v_{GS1} = v_{IN}$$

$$-v_{GS2} = v_{OUT}$$

thus:

$$A_V = \frac{v_{OUT}}{v_{IN}} = -\frac{g_{m1}}{g_{m2}}$$

Example:



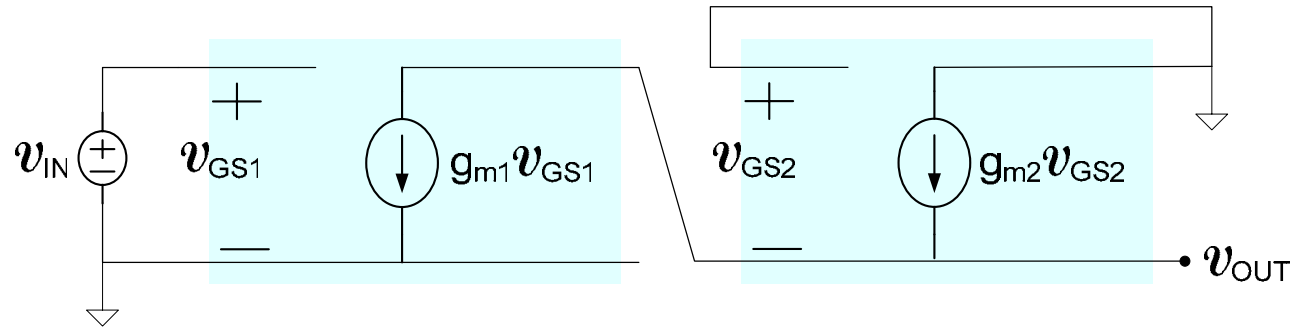
Analysis: *Small-signal circuit*

$$A_V = \frac{v_{OUT}}{v_{IN}} = -\frac{g_{m1}}{g_{m2}}$$

Recall: $g_m = -\sqrt{2I_D \mu C_{ox}} \sqrt{\frac{W_1}{L_1}}$

$$A_V = -\frac{\sqrt{2I_D \mu C_{ox} \frac{W_1}{L_1}}}{\sqrt{2I_D \mu C_{ox} \frac{W_2}{L_2}}} = -\sqrt{\frac{W_1}{W_2}} \sqrt{\frac{L_2}{L_1}}$$

Example:



Analysis: *Small-signal circuit*

$$A_V = \frac{v_{OUT}}{v_{IN}} = -\frac{g_{m1}}{g_{m2}}$$

Recall:

$$A_V = -\sqrt{\frac{W_1}{W_2}} \sqrt{\frac{L_2}{L_1}}$$

If $L_1=L_2$, obtain

$$A_V = -\sqrt{\frac{W_1}{W_2}} \sqrt{\frac{L_2}{L_1}} = -\sqrt{\frac{W_1}{W_2}}$$

The width and length ratios can be accurately set when designed in a standard CMOS process